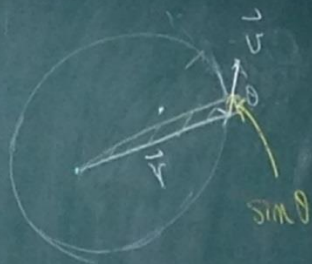


$$\frac{d(\frac{1}{2} r v \sin \theta)}{dt}$$

$$\boxed{\frac{1}{2} r v}$$



$$dA = (\frac{1}{2} r)(v dt \sin \theta)$$

$$\frac{dA}{dt} = \frac{1}{2} r v \sin \theta$$

$$|\vec{L}| = \vec{r} \times \vec{p} = \vec{r} \times (m\vec{v}) = m|\vec{r} \times \vec{v}| = \underline{m r v \sin \theta} \frac{1}{2}$$

$$\frac{d\vec{L}}{dt} = 0$$

$$-(\frac{1}{2} M + m) R^2 \omega^2$$

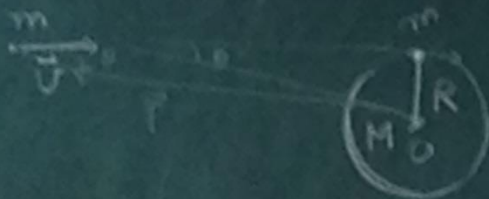
$$m \frac{v^2}{r} = G \frac{Mm}{r^2} \Rightarrow$$

$$v^2 = G \frac{M}{r}$$

$$T^2 = \frac{4\pi}{GM} r^3$$

$$\frac{2\pi r}{v} = T \rightarrow v = \frac{2\pi r}{T} \quad \frac{4\pi r^2}{T^2} = G \frac{M}{r^2}$$





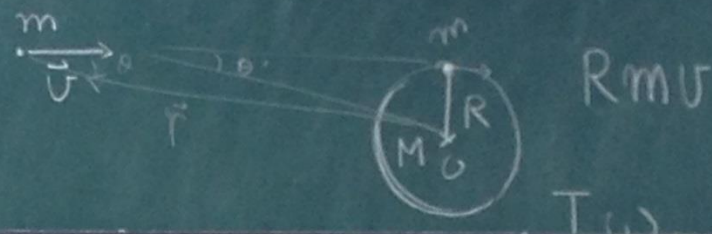
$$Rm\omega$$

$$I\omega$$

$$\left(\frac{1}{2}MR^2 + mR^2\right)\omega$$



$$\frac{d\left(\frac{1}{2}I\omega\right)}{dt}$$
$$\left[\frac{1}{2}I\right]$$



$$RmU = \left(\frac{1}{2}M + m\right) R^2 \omega$$

$$\omega = \frac{m}{\frac{1}{2}M + m} v$$

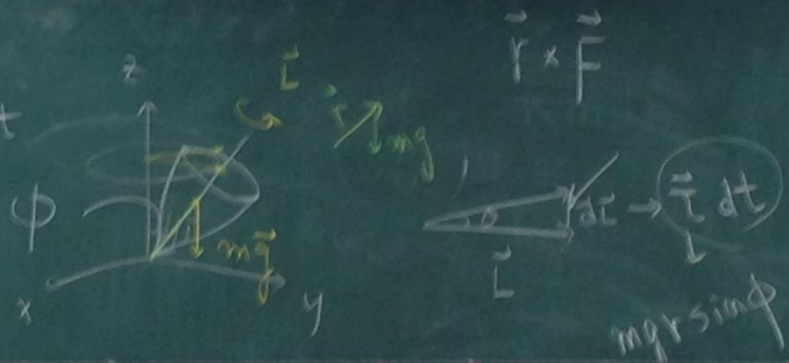
$$K_i - K_f = \frac{1}{2}mv^2 - \frac{1}{2}I\omega^2 = \frac{1}{2}mv^2 - \frac{1}{2}\left(\frac{1}{2}M + m\right)R^2\omega^2$$

$$= \frac{mM}{2M + 4m} v^2$$

$$\Omega = \frac{d\theta}{dt} = \frac{dL}{L \sin\phi dt}$$

$$L \sin\phi d\theta = dL$$

$$\Omega = \frac{dL}{L \sin\phi}$$



$$Rmv = \left(\frac{1}{2}M + m\right) R^2 \omega$$

$$\omega = \frac{m}{\frac{1}{2}M + m} v$$

$$K_k - K_f = \frac{1}{2}mv^2 - \frac{1}{2}I\omega^2 = \frac{1}{2}mv^2 - \frac{1}{2}\left(\frac{1}{2}M + m\right)R^2\omega^2$$

$$M \frac{v^2}{r} = G \frac{Mm}{r^2} \Rightarrow$$

$$v^2 = G \frac{M}{r}$$

$$T^2 = \frac{4\pi}{GM} r^3$$

$$\frac{2\pi r}{v} = T \rightarrow v = \frac{2\pi r}{T} \quad \frac{4\pi r^2}{T^2} = G \frac{M}{r^2}$$



$$R^2 \omega^2 =$$