

Lecture 11

6.976 Flat Panel Display Devices

Physics of Liquid Crystals I

Outline

- **Polarization Devices**
- **Jones Matrix Method**
- **Liquid Crystals**

References

- Jin Au Kong, Electromagnetic Wave Theory, EMW Publishing, Cambridge, MA, USA
- B. E. A. Saleh and M. C. Teich, Fundamentals of Photonics, John Wiley & Sons, New York
- E. Hecht, Optics, Addison-Wesley Publishing
- Peter J. Collings and Michael Hird, Introduction to Liquid Crystals-Chemistry and Physics, Taylor and Francis, 1997
- D. J. Channin and A. Sussman, Liquid Crystal Displays, LCD, Chapter 4 in Display Devices, Ed. Jacques I. Pankove, Springer-Verlag, 1980.
- P. Yeh and C. Gu, Optics of Liquid Crystal Displays, John Wiley & Sons, New York, 1999.

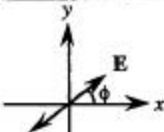


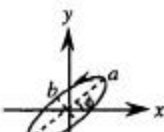
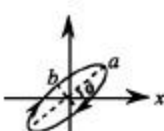
Jones Vectors

$$\mathbf{J} = \begin{pmatrix} \hat{\mathbf{e}}_x A_x e^{jd_x} \\ \hat{\mathbf{e}}_y A_y e^{jd_y} \end{pmatrix} \begin{pmatrix} \hat{\mathbf{u}} \\ \hat{\mathbf{u}} \end{pmatrix}$$

From this we can determine intensity

$$\mathbf{I} = |A_x|^2 + |A_y|^2$$

Table 4.1. Jones Vectors

Polarization State	Jones Vector
	$\begin{pmatrix} \cos \phi \\ \sin \phi \end{pmatrix}$
	$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}$
	$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$
	$\begin{pmatrix} a \cos \phi + ib \sin \phi \\ a \sin \phi - ib \cos \phi \end{pmatrix}$
	$\begin{pmatrix} a \cos \phi - ib \sin \phi \\ a \sin \phi + ib \cos \phi \end{pmatrix}$

Note: a and b are the principal axes of the ellipse.

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Jones Matrix Formulation

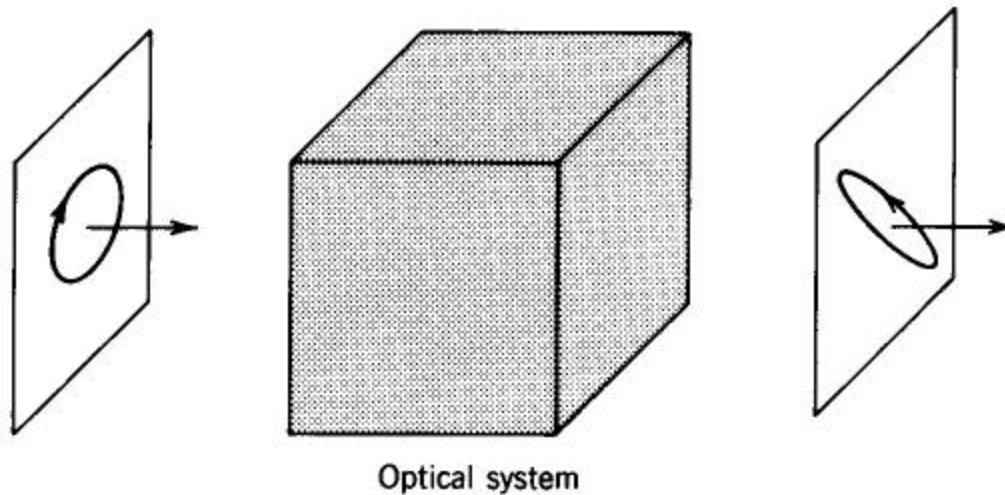


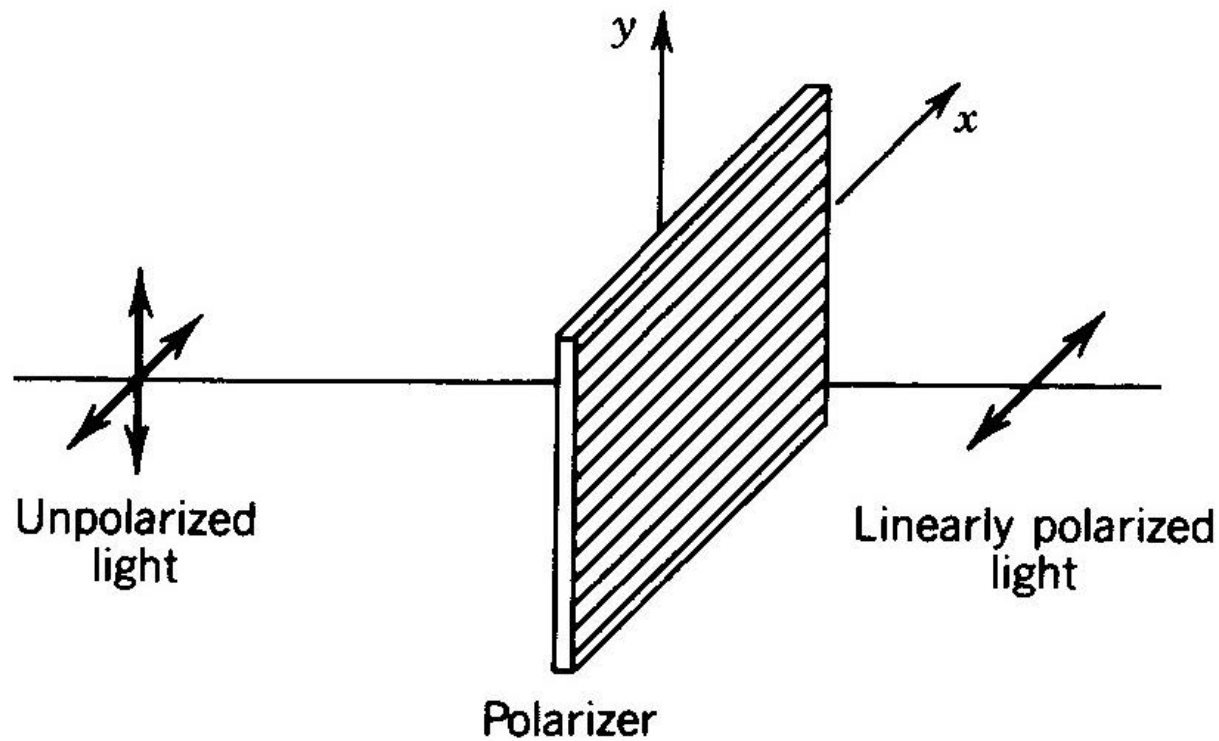
Figure 6.1-4 An optical system that alters the polarization of a plane wave.

Saleh & Teich

$$\begin{pmatrix} \hat{e}_1 A_{2x} \\ \hat{e}_2 A_{2y} \end{pmatrix} = \begin{pmatrix} \hat{e}_1 T_{11} & \hat{e}_1 T_{12} \\ \hat{e}_2 T_{21} & \hat{e}_2 T_{22} \end{pmatrix} \begin{pmatrix} A_{1x} \\ A_{1y} \end{pmatrix}$$

$$\mathbf{J}_2 = \mathbf{T} \mathbf{J}_1$$

Linear Polarizer



$$\mathbf{T} = \begin{pmatrix} \hat{e}_1 & 0 \\ \hat{e} & 0 \\ \hat{e}_0 & 0 \end{pmatrix} \begin{pmatrix} \hat{u} \\ \hat{u} \end{pmatrix}$$

Figure 6.1-5 The linear polarizer.

Saleh & Teich

Wave Retarder

$$\mathbf{T} = \begin{pmatrix} e^{j\mathbf{f}} & 0 \\ \hat{\mathbf{e}} & e^{-j\mathbf{G}} \\ \hat{\mathbf{e}} & \hat{\mathbf{u}} \\ \hat{\mathbf{e}} & \hat{\mathbf{u}} \end{pmatrix}$$

$$\mathbf{G} = \frac{2\mathbf{p}}{\mathbf{l}} (\mathbf{n}_s - \mathbf{n}_f) \mathbf{d}$$

$$\mathbf{T} = e^{-j\mathbf{f}} \begin{pmatrix} e^{-j\mathbf{G}/2} & 0 \\ \hat{\mathbf{e}} & \hat{\mathbf{u}} \\ \hat{\mathbf{e}} & 0 \\ \hat{\mathbf{e}} & e^{+j\mathbf{G}/2} \end{pmatrix}$$

\mathbf{f} = absolute phase change

$\tilde{\mathbf{X}}$ = relative phase change

Half-Wave Retarder Plate

$$\mathbf{T} = \begin{pmatrix} e^{-j} & 0 \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & j\hat{u} \end{pmatrix}$$

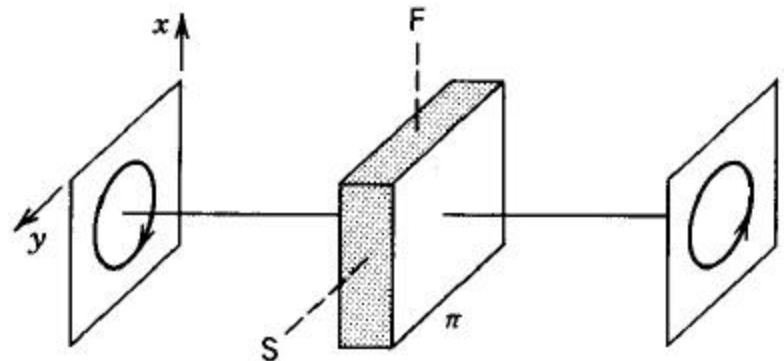
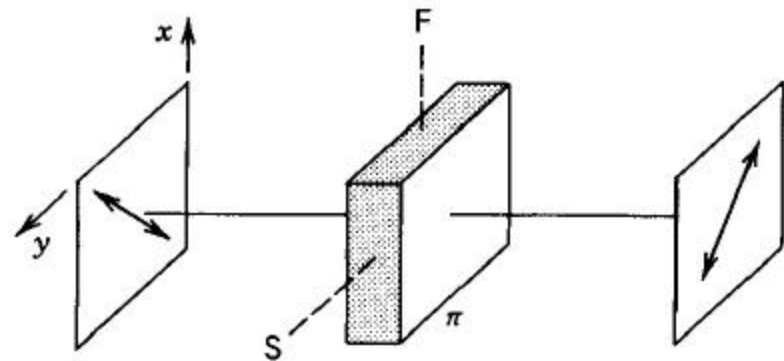
$$G = \frac{2p}{l} (n_s - n_f)d = p$$

$$\begin{pmatrix} e^{-j} & 0 \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & j\hat{u} \end{pmatrix} \begin{pmatrix} e^{j} & 0 \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & -j\hat{u} \end{pmatrix} = \begin{pmatrix} e^{-j} & -j \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & -1 \end{pmatrix}$$

Polarization rotated by 90°

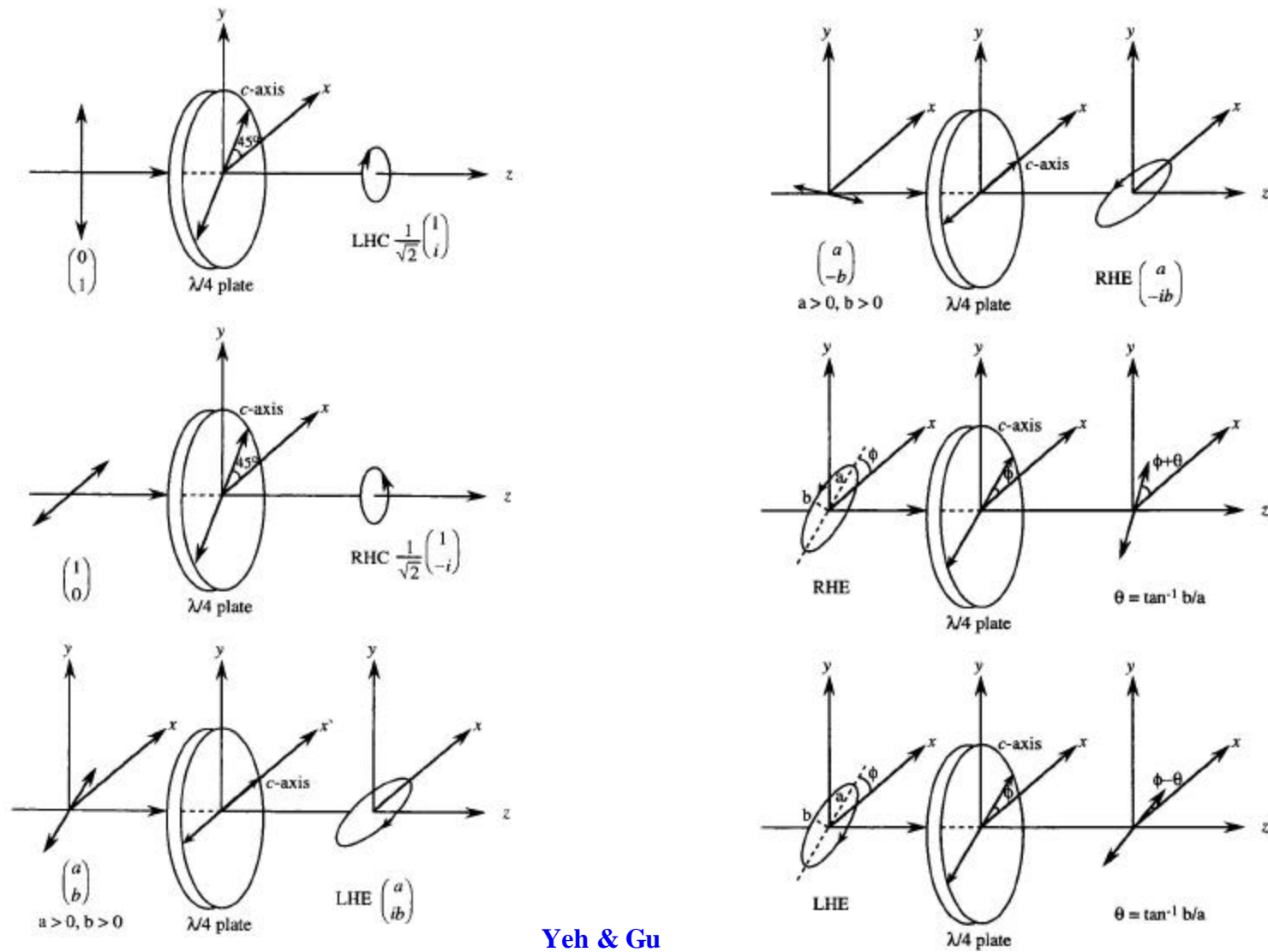
$$\begin{pmatrix} e^{-j} & 0 \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & j\hat{u} \end{pmatrix} \begin{pmatrix} e^{j} & 0 \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & -j\hat{u} \end{pmatrix} = \begin{pmatrix} e^{-j} & -j \\ \hat{e} & \hat{u} \\ \hat{e} & 0 \\ 0 & -1 \end{pmatrix}$$

R-circularly polarized \Rightarrow
L-circularly polarized



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Effect of Quarter Wave Plate



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Polarization Rotators

$$\mathbf{T} = \begin{pmatrix} \hat{e} \cos q & -\sin q \hat{u} \\ \hat{e} \sin q & \cos q \hat{u} \end{pmatrix}$$

Takes linearly polarized wave

$$\begin{pmatrix} \hat{e} \cos q_1 \hat{u} \\ \hat{e} \sin q_1 \hat{u} \end{pmatrix}$$

converts to

$$\begin{pmatrix} \hat{e} \cos q_2 \hat{u} \\ \hat{e} \sin q_2 \hat{u} \end{pmatrix}$$

$$\text{where } q_2 = q_1 + q$$

Coordinate Transformation

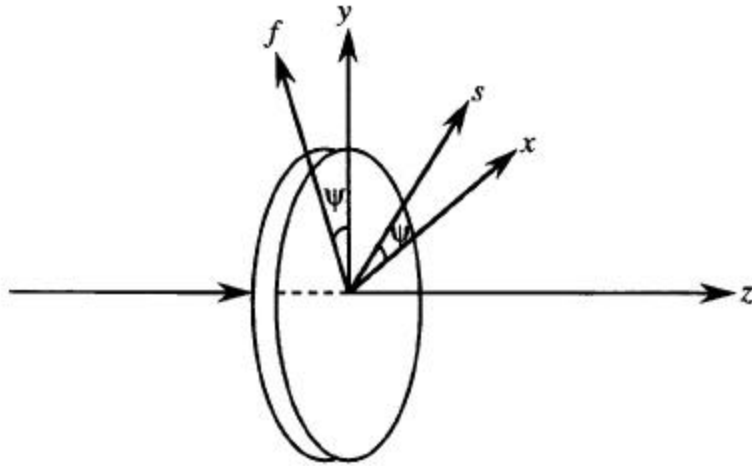


Figure 4.1. A retardation plate with azimuth angle ψ .

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If $\psi=45^\circ$

$$\mathbf{R}(45^\circ) = \frac{1}{\sqrt{2}} \begin{pmatrix} \hat{e}_1 & 1 & 1 \\ \hat{e}_2 & -1 & 1 \end{pmatrix} \begin{matrix} \hat{u} \\ \hat{u} \\ \hat{u} \end{matrix}$$

For half - wave plate

$$\mathbf{T}_{xy} = \frac{1}{\sqrt{2}} \begin{pmatrix} \hat{e}_1 & 1 & -1 \\ \hat{e}_2 & 1 & 1 \end{pmatrix} \begin{matrix} \hat{u} \\ \hat{u} \\ \hat{u} \end{matrix} \begin{matrix} \hat{e}_1 & 1 & 1 \\ \hat{e}_2 & -1 & 1 \end{matrix} \begin{matrix} \hat{u} \\ \hat{u} \\ \hat{u} \end{matrix} = \begin{pmatrix} \hat{e}_1 & 0 & -j \\ \hat{e}_2 & -j & 0 \end{pmatrix} \begin{matrix} \hat{u} \\ \hat{u} \\ \hat{u} \end{matrix}$$

$$\begin{pmatrix} \hat{e}_s \\ \hat{e}_f \end{pmatrix} \begin{matrix} \hat{u} \\ \hat{u} \end{matrix} = \begin{pmatrix} \hat{e}_1 \cos y & \sin y \\ \hat{e}_2 - \sin y & \cos y \end{pmatrix} \begin{pmatrix} \hat{e}_x \\ \hat{e}_y \end{pmatrix} \begin{matrix} \hat{u} \\ \hat{u} \end{matrix}$$

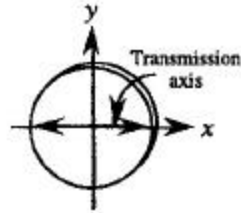
$$\mathbf{R}(y) = \begin{pmatrix} \hat{e}_1 \cos y & \sin y \\ \hat{e}_2 - \sin y & \cos y \end{pmatrix} \begin{matrix} \hat{u} \\ \hat{u} \end{matrix}$$

$$\mathbf{T}_{xy} = \mathbf{R}(-y) \mathbf{T}_{sf} \mathbf{R}(y)$$

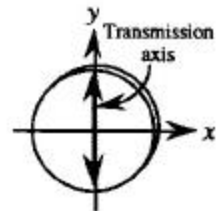
Jones Matrices

(Polarizers)

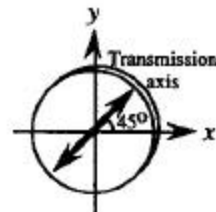
Polarizers



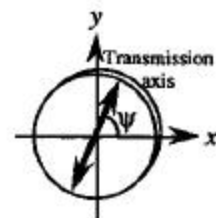
$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$



$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$



$$\begin{pmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{pmatrix}$$



$$R(-\psi) \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} R(\psi)$$

$$= \begin{pmatrix} \cos \psi & -\sin \psi \\ \sin \psi & \cos \psi \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \cos \psi & \sin \psi \\ -\sin \psi & \cos \psi \end{pmatrix}$$

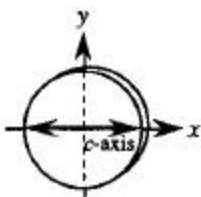
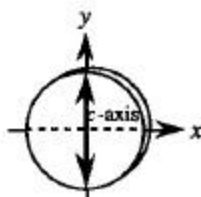
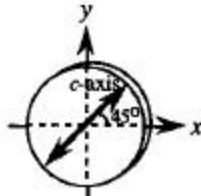
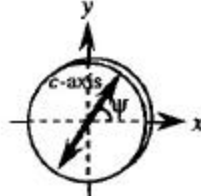
$$= \begin{pmatrix} \cos \psi & -\sin \psi \\ \sin \psi & \cos \psi \end{pmatrix} \begin{pmatrix} \cos \psi & \sin \psi \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \cos^2 \psi & \cos \psi \sin \psi \\ \sin \psi \cos \psi & \sin^2 \psi \end{pmatrix}$$

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* Here we assume that the c axis is perpendicular to the z axis (i.e., $\theta = 90^\circ$). In general, E (3.3-4) must be used for n_e if $\theta \neq 90^\circ$.

Jones Matrices (Wave Plates)

Table 4.2. Jones Matrices

Optical Element	Jones Matrices
<i>Wave Plates</i>	
	$\Gamma \equiv \frac{2\pi}{\lambda} (n_e - n_o)d$ $\begin{pmatrix} e^{-i\Gamma/2} & 0 \\ 0 & e^{i\Gamma/2} \end{pmatrix}$
	$\begin{pmatrix} e^{i\Gamma/2} & 0 \\ 0 & e^{-i\Gamma/2} \end{pmatrix}$
	$\begin{pmatrix} \cos \frac{\Gamma}{2} & -i \sin \frac{\Gamma}{2} \\ -i \sin \frac{\Gamma}{2} & \cos \frac{\Gamma}{2} \end{pmatrix}$
	$R(-\psi) \begin{pmatrix} e^{-i\Gamma/2} & 0 \\ 0 & e^{i\Gamma/2} \end{pmatrix} R(\psi)$ $= \begin{pmatrix} \cos \psi & -\sin \psi \\ \sin \psi & \cos \psi \end{pmatrix} \begin{pmatrix} e^{-i\Gamma/2} & 0 \\ 0 & e^{i\Gamma/2} \end{pmatrix} \begin{pmatrix} \cos \psi & \sin \psi \\ -\sin \psi & \cos \psi \end{pmatrix}$

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